Elective IV (Open Elective)
Under BOS (Electronics)

ADVANCED AUTOMOTIVE ELECTRONICS

Teaching Scheme:
Lectures: 3 Hrs/ Week

Examination Scheme:
In Semester Assessment:
Phase I : 30

End Semester Examination:
Phase II: 70

Course Objectives

1. To understand the concepts of Automotive Electronics and it's evolution and trends
2. Automotive systems & subsystems overview.
3. To understand sensors and sensor monitoring mechanisms aligned to automotive systems, different signal conditioning techniques, interfacing techniques and actuator mechanisms.
4. To understand, design and model various automotive control systems using Model based development technique.
5. To understand role of Microcontrollers in ECU design and choice of appropriate Hardware and Software.
6. To describe various communication systems, wired and wireless protocols used in vehicle networking.
7. To understand Safety standards, advances in towards autonomous vehicles.
8. To understand vehicle on board and off board diagnostics.

Course Outcomes

After successfully completing the course students will be able to:

1. Obtain an overview of automotive components, subsystems, design cycles, communication protocols and safety systems employed in today's automotive industry
2. Interface automotive sensors and actuators with microcontrollers
3. Develop, simulate and integrate control algorithms for ECUs with hardware

UNIT 1: Automotive Systems, Design Cycle and Automotive Industry Overview

Overview of Automotive Industry: Leading players, Automotive supply chain, Global challenges, Role of technology in Automotive Electronics and interdisciplinary design, Tools and processes.

Introduction to Modern Automotive Systems and need for electronics in automobiles and application areas of electronic systems in modern automobiles. Spark and Compression Ignition Engines: Ignition systems, Fuel delivery systems, Engine control functions, Fuel control, Electronic systems in engines.

Automotive transmissions: Transmission fundamentals, Types MT, AT, CVT and DCT. Vehicle Braking Fundamentals: Vehicle dynamics during braking, Hydraulic brake system components, Introduction to antilock braking systems.

Steering Control: Steering system basics, Fundamentals of electronically controlled power steering, Electronically controlled hydraulic systems and electric power steering systems, Passenger safety and convenience, Occupant protection systems, Tyre pressure monitoring systems.

ECU Design Cycle: V-Model development cycle, Components of ECU, Examples of ECU on chassis, and in body electronics, infotainment and clusters. Overview of hybrid vehicles.

UNIT 2: Automotive Sensors and Actuators

Systems Approach to Control and Instrumentation: Concept of a system, Analog and digital systems, Basic measurement systems, Analog and digital signal processing, Sensors, Sensor characteristics, Sensor response, Sensor error, Redundancy of sensors in ECUs, Avoiding redundancy, Sensor modeling, Smart Nodes.

Examples of Sensors: Accelerometers, Wheel speed, Brake pressure, Seat occupancy, Engine speed, Steering wheel angle, Vehicle speed, Throttle position, Turbine speed, Temperature, Mass air flow (MAF) rate, Exhaust gas oxygen concentration, Throttle plate angular position, Crankshaft angular position/RPM, Manifold Absolute Pressure (MAP), Differential exhaust gas pressure and Air bag sensors.

Actuators used: Solenoids, Various types of electric motors and piezoelectric force generators.

Examples of Actuators: Relays, Solenoids and motors. Chassis control systems and Automatic transmission control systems.

UNIT 3: Microcontrollers/Microprocessors in Automotive domain,

Critical review and overview of development within the automotive context of microprocessors, microcontrollers and digital signal processors (architecture of 8/16 bit microcontrollers with emphasis on Ports, Timer/Counters, Interrupts, Watchdog timers and PWM). Criteria to choose the right microcontroller/processor for various automotive applications. Understanding various architectural attributes relevant to automotive applications. Automotive grade processors viz. Renesas, Quorivva, Infineon. Understanding and working on tool chains for different processors. Development of control algorithms for different automotive subsystems, Look-up tables and maps, Need of maps, Procedure to generate maps, Fuel maps/tables, Ignition maps/tables, Engine calibration, Torque table, Dynamometer testing.

UNIT 4: Communication protocols, Infotainment systems

Communication protocols: Overview of automotive communication protocols, CAN, LIN , Flex Ray, MOST , Ethernet, D2B and DSI, Communication interface with ECUs, Interfacing techniques and

Interfacing with infotainment gadgets, Relevance of Protocols such as TCP/IP for automotive applications, Wireless LAN standards such as Bluetooth, IEEE 802.11x communication protocols for automotive applications. Infotainment Systems: Application of telematics in automotive domain, Global positioning systems (GPS) and General packet radio service (GPRS).

UNIT 5: Automotive Control Systems and Model Based Development:

Automotive Control System & Model Based Development: Control system approach in Automotive Electronics, Analog and digital control methods, Modelling of linear systems, System responses, Modelling of Automotive Systems with simple examples. Model based Development: Introduction to MATLAB, Simulink and SIMSCAPE tool boxes, Model-Based Design for a small system, Motor Model, Generator Model, Controller Model, SimDriveline, Introduction to Simulink simulations, Exploring the system response using different control methods, Tuning the system, Exploring system limitations, Understanding and refining motor models, Real time simulations on a simple target (Arduino / Rasberry Pi etc), Study of modeling and simulation of any one Automotive System.

UNIT 6: Safety Systems in Automobiles and Diagnostic Systems

Active Safety Systems: ABS, TCS, ESP, Brake assist, etc. Passive Safety Systems: Airbag systems, Advanced Driver Assistance Systems (ADAS): Combining computer vision techniques as pattern recognition, feature extraction, learning, tracking, 3D vision, etc. to develop real-time algorithms able to assist the driving activity. Examples of Assistance Applications: Lane Departure Warning, Collision Warning, Automatic Cruise Control, Pedestrian Protection, Headlights Control, Connected Cars technology and trends towards Autonomous vehicles.

Functional Safety: Need for safety systems, Safety concept, Safety process for product life cycle, Safety by design, Validation

Diagnostics: Fundamentals of Diagnostics, Basic wiring system and Multiplex wiring system, Preliminary checks and adjustments, Self-diagnostic system, Fault finding and corrective measures, Electronic transmission checks and Diagnosis, Diagnostic procedures and sequences, On-board and off-board diagnostics in Automobiles, OBDII, Concept of DTCs, DLC, MIL, Freeze Frames, History Memory, Diagnostic tools, Diagnostic protocols KWP2000 and UDS.

Text Books:

1. Williams. B. Ribbens: “Understanding Automotive Electronics”, 6th Edition, Elsevier Science, Newnes Publication, 2003.
2. Robert Bosch: “Automotive Electronics Handbook”, John Wiley and Sons, 2004.

Reference books:

1. Ronald K Jurgen: “Automotive Electronics Handbook”, 2nd Edition, McGraw-Hill, 1999.
2. James D. Halderman: “Automotive Electricity and Electronics", PHI Publication.

3. Terence Rybak & Mark Stefika: “Automotive Electromagnetic Compatibility (EMC)”, Springer, 2004.
4. Allan Bonnick: “Automotive Computer Controlled Systems, Diagnostic Tools and Techniques”, Elsevier Science, 2001.
5. Uwe Kieneke and Lars Nielsen: “Automotive Control Systems: Engine, Driveline and Vehicle”, 2nd Edition, Springer Verlag, 2005.
6. David Alciatore & Michael Histand: "Introduction to Mechatronics and Measurement Systems (SIE)”, TMH, 2007.
7. Iqbal Husain: "Electric and Hybrid Vehicles: Design Fundamentals”, CRC Press, 2003.
8. Tom Denton: "Advanced Automotive Diagnosis”, 2nd Edition, Elsevier, 2006.
9. G. Meyer, J. Valldorf and W. Gessner: "Advanced Microsystems for Automotive Applications”, Springer, 2009.
10. Tracy Martin: “How to Diagnose and Repair Automotive Electrical Systems" Motor Books / MBl Publishing Company, 2005.
11. Mehrdad Ebsani, Ali Emadi & Yimin Gao: “Modern Electronic Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design", 2nd Edition, CRC Press, 2009.
12. Marc E. Herniter and Zac Chambers: “Introduction to Model Based System Design”, Rose-Hulman Institute of Technology.